

SURVEY NOTES

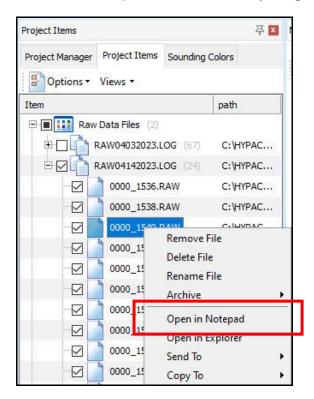
Testing for Timing Errors - Checking the Driver Setup for the CEESCOPE[™] and CEE ECHO[™] when using HYPACK.

Owing to the unique time-stamped data output of the CEESCOPE[™] and CEE ECHO[™], HYPACK software offers several ways to configure hardware drivers for these devices. If ancillary equipment is used, such as a heave sensor or side scan sonar, driver configuration may be different versus an echosounder-only setup. However IN ALL CASES, the HYPACK RAW file must show a consistent timebase, with the data message recorded time increasing as the data are written. We recommend that the driver setup be checked prior to each survey. This document explains how incorrect driver setups may be detected by recording and checking a test RAW file. Even if data are recorded with incorrect driver setup, HYPACK has a tool to correct the time error.

The CEESCOPE[™] and CEE ECHO[™] can generate a precise GNSS-derived time stamp that is usually applied to every line of data and each binary echogram ping packet. The POS time stamp as applied to GNSS data output by the CEESCOPE is shown below. Time is expressed in seconds past midnight based on the CEESCOPE system time. HYPACK refers to the special CEE GNSS output as a "User Modified NMEA Message".

POS 42649023 \$GPGGA,015055.00,3338.9114522,S, 15109.8404898, E,4,14,0.8,2.074,M,23.20,M,02,0006*45

To check that no HYPACK timing errors are present, first record about 10-20 seconds of RAW data. Then, inspect the RAW file by a right click on the RAW file and "Open in Notepad":



This example below shows a correctly configured hardware setup. The incoming messages will repeat based on the output rate of each device. The device / driver number is listed as 0, 1, 2....

The time of the data record is column 3 in seconds past midnight. This time may be either PC time or time from the CEESCOPE echo sounder and may or may not be synced to GNSS time. In this document, it is not important to discuss the driver setup options as the same conditions must be achieved independent of the driver selection.

The key messages used in data processing are:

EC1 – Echosounder EC depth single channel (1), dual channel (2)

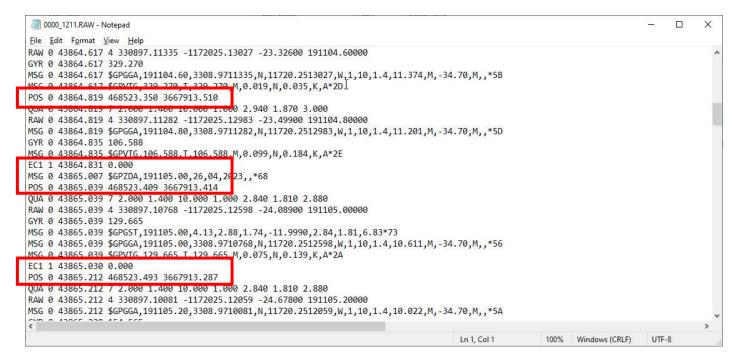
POS - Calculated XY position

Other messages are listed below. The time of these messages is not relevant in this discussion:

MSG – GPS NMEA message (used to determine POS)

GYR – Heading QUA – Satellite quality information

RAW – position data Lat / Long



The EC1 and POS messages MUST ALWAYS increase in time as the file is written. If the time base used for the GNSS and echosounder drivers is the same then there is no way that a new RAW file message line can be written at a time earlier than the previous one.

If the driver setup is wrong, and different time bases are used, then it will cause data to go either backwards or forwards in time for one driver versus the other. SMALL TIME offsets might be undetectable. LARGE TIME offsets will cause the Single Beam Editor SBMAX to fail to load.

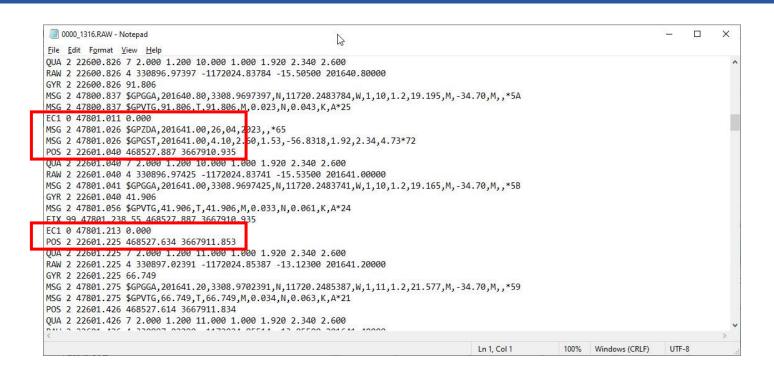
In the below example, a small time offset is seen with at least 0.015s error. The EC1 line is written before the POS line however the time of the message is 0.015s later. A small time offset like this might arise when the PC time is very recently synchronized with the Windows server and happens to be close to the time used by the CEE device, based on GPS time. This offset is unlikely to be noticeable in data editing, however the driver setup is still wrong.

0000_1201.RAW - Notepad			<u>1997</u> 33	\times
<u>File Edit Format View Help</u>				
RAW 2 43310.000 4 330897.07784 -1172025.15843 -23.55500 1 915	0.00000			~
GYR 2 43310.044 322.300				
MSG 2 43310.044 \$GPGGA,190150.00,3308.9707784,N,11720.2515843	,W,1,10,1.3,11.145,M,-34.7	0,M,,*5F		
MSG 2 43310.044 \$GPVTG,322.300,T,322.300,M,0.086,N,0.159,K,A*				
EC1 0 43310.215 0.000	91 C			
POS 2 43310.200 468522.922 3667912.84	43310.215 - 43310.2	00 = +0.015 offset		
QUA 2 43310.200 7 2.000 1.300 10.000 1.000 2.630 1.760 2.670				
RAW 2 43310.200 4 330897.07694 -1172025.15724 -23.53400 19015	0.20000			
GYR 2 43310.232 152.847				
MSG 2 43310.232 \$GPGGA,190150.20,3308.9707694,N,11720.2515724	,W,1,10,1.3,11.166,M,-34.7	0,M,,*52		
MSG 2 43310.232 \$GPVTG,152.847,T,152.847,M,0.089,N,0.165,K,A*	20			
FIX 99 43310.339 45 468522.922 3667912.848				
EC1 0 43310.415 0.000				
POS 2 43310.399 468522.900 3667912.865				
QUA 2 43310.399 7 2.000 1.300 10.000 1.000 2.630 1.760 2.670				
RAW 2 43310.399 4 330897.07785 -1172025.15861 -23.53800 19015	0.40000			
GYR 2 43310.436 285.370				
MSG 2 43310.436 \$GPGGA,190150.40,3308.9707785,N,11720.2515861	,W,1,10,1.3,11.162,M,-34.7	0,M,,*5F		
MSG 2 43310.436 \$GPVTG,285.370,T,285.370,M,0.054,N,0.099,K,A*				
EC1 0 43310.614 0.000				~
				>

In this next example, a larger time offset is seen with at least 5.017s error. This may be a result of using an acquisition PC that has not been connected to a Windows server (internet) for a long time, leading to a larger divergence from GNSS time. The single beam editor SBMAX will load this data however RAW and EDITED soundings will appear at different places on the map view and the offset will likely be obvious.

0000_1550.RAW - Notepad	ii.			3 <u>0</u>		×
<u>File Edit Format View H</u> elp						
EC2 0 57004.939 27.165 27.165						^
SMI 0 57004.939 2 27.17 27.17						
GYR 1 56999.811 103.810						
MSG 1 57005.056 \$GPVTG,103.810,T,103.810,M,2.690,N,4.981,K,D*2F						
ETX 99 57005 115 291 1905550 724 684389 780						
EC2 0 57005.138 27.198 27.198						
SMI 0 57005.138 2 27.20 27.20						
POS 1 57000.031 1905554.827 684388.554						
QUA 1 57000.031 7 1.000 1.000 8.000 9.000 0.840 0.690 0.840						
RAW 1 57000.031 4 413269.54000 -824379.67000 139.61000 195000.00000						
GYR 1 57000.031 105.034						
MSG 1 57005.290 \$GPZDA,195000.00,14,04,2023,,*69						
MSG 1 57005.290 \$GPGST,195000.00,1.10,0.84,0.69,0.3025,0.84,0.69,1.58*62						
MSG 1 57005.290 \$GPGGA,195000.00,4132.6954,N,08243.7967,W,9,08,1.0,175.51,N	1,-35.90,M,05,0131*59					~
< c						2
	Ln 1, Col 1	100%	Windows (CRLF)	UTF	8	

In the final example, a huge time offset is seen. This may be the result of the CEE device being set at UTC and the PC running on local time. The single beam editor SBMAX will likely be unable to load this data and will fail on startup.



If a timing issue is detected, consult CEE HydroSystems' latest setup guides posted on the CEE website "Knowledge Base", or contact CEE HydroSystems directly for assistance.

If data have been collected and the timing is determined to be in error, a simple fix is available. In HYPACK, go to: Utilities / files work / RAW Data adjustments > adjust depths > dTime

Did 🔹 🔁	Extension	New Exten	ision ZZZ			
Adjust Depths		🗌 Adjust Heave, Pi	tch, Roll	Recalculate GPS		
dDepth	0.0	dHeave(m)	0.0	dLat (sec)	0.0	
dTime (sec)	0.0	dPitch (deg)	0.0	dLon (sec)	0.0	
Factor	1.0	dRoll (deg)	0.0	dTime (sec)	0.0	
Adjust Positions		dTime (sec)	0.0	Adjust Gyro		
DX	0.0	Invert Heave		dTheta (deg)	0.0	
DY	0.0	Invert Roll		dTime (sec)	0.0	
dTime (sec) 0.0		Adjust Tide	18	Adjust Fix Marks		
		dTide	0.0	dTime (sec)	0.0	
		dTime (sec)	0.0			

This will write new RAW files with the extension .ZZZ and it will NOT delete the original RAW files.